1. (10 points) Suppose that you have an application in which you want to use B-trees. Suppose that the computer you will be using has disk blocks holding 2048 bytes, the key is 4 bytes long, each child pointer (which is a disk block id) is 4 bytes, the parent pointer is 4 bytes and the data record reference (which is a disk block id along with a offset within the block) is 8 bytes.

You have an application in which you want to store 1,000,000,000 items in your B-tree. What value would you select for \( t \)? (Show how you derived it.) What is the maximum number of disk pages that will be brought into main memory during a search? Remember that the root is kept in main memory at all times.

2. Consider the following B-tree. Each of the three problems below will use this B-tree as its starting point.

```
    D L
   /   |
  B    H
   |   /   |
  P R T
```

(a) (10 pts) Show the B-tree that results from inserting Y, F, X, Z (in that order) into the following B-tree where the minimum branching factor \( t = 2 \). Circle (or in some way clearly mark) the B-tree obtained after each insertion is completed.

(b) (10 pts) Show the B-tree that results from deleting B, then D, and then H from the B-tree shown before part (a).

(c) (5 pts) Show both of the two legal ways to represent the original B-tree as a red-black tree. You can indicate the color of each node by circling it with red or black or just by putting a “r” or “b” next to it. The B-tree has 3 levels and thus your red-black tree should have exactly 3 black nodes on every path from the root to the leaf. Also, there should never should be a red node with a red parent.

3. (30 points) For the following problem you are to pick a data structure that is best suited for the problem (i.e. the required operation will run as efficiently as possible). The following components should be clearly given in each of your solutions. Your grade will also depend on you selecting the most efficient data structure possible.

- You should very clearly describe your data structure choice, including all decisions about how the data structure is to be applied (e.g. what is used as the key, what is the associated data, table size and collision resolution choice for hashtables...).
- You should clearly describe how each of the provided operations will be implemented AND analyze the efficiency for each of the operations Do NOT give an code or even pseudo-code. Assume the person reading your solution is familiar with all of the material we have covered. You only need to describe any new methods or variations of standard methods that you need.
Briefly discuss your choice of data structures. In particular why did you choose the data structure that you choose? Convince us that it was a good choice.

Suppose you have a multimedia document with a set of video segments that are scheduled to play. Each segment \( s \) consists of a beginning time \( b \), an ending time \( e \), and a reference to a video object \( v \). You must support the below operations.

- Given a new segment \( s = (b, e, v) \) determine if \( s \) overlaps any segment currently scheduled to play.
- Insert a new segment \( s = (b, e, v) \) into the schedule if it does not overlap any currently scheduled segments. (If it does overlap any segment then just report that it cannot be inserted).
- Remove the segment with the earliest beginning time, returning a reference to the associated video segment.

**Challenge Problem: (5 points)**

A common implementation of sequential files on disk has each block point to its successor, which may be any block on the disk. This method requires a constant amount of time to write a block, to read the first block in the file, and to read the \( i \)th block, once you have read the \( i-1 \)st block. Reading the \( i \)th block from scratch, requires time proportional to \( i \). Show how by adding just one additional pointer per node you can keep all the other properties, but allow the \( i \)th block to be read in time \( O(\log i) \).